

# Settlement Estimation of Multiple Footings in Sands

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**ABSTRACT:** Shallow foundations are popular for various building structures and typically consist of multiple footings, often in close proximity. The most widely used methods for the estimation of footing settlement have been developed for an isolated footing and do not provide a way to account for interaction between adjacent footings. In this paper, a method of settlement estimation that takes account of the proximity of neighboring footing is presented based on Schmertmann's framework. Three-dimensional non-linear finite element analyses are performed to obtain the load-settlement responses and strain distributions in the foundation soils for multiple footings separated by different footing edge-to-edge distances. Various multiple footing configurations were considered in the finite element analyses.

## 1 INTRODUCTION

Footings are often used for foundations of various structures. The typical design procedure of a footing includes the assessment of limit bearing capacity and the estimation of settlement under working loads. In routine practice, the estimation of footing settlement in sands is commonly based on the linear-elastic approach using a representative elastic modulus. In the conventional approach for the footing settlement estimation, interactions between adjacent footings are not specifically taken into account. However, it is noted that shallow foundations for typical building structures consist of multiple footings, often in close proximity. The mechanical interaction between adjacent footings generates settlements greater than those for isolated footings, and therefore neglect of the interactions between adjacent footings may result in unconservative footing design.

Schmertmann's method is one of several methods (Meyerhof 1965, Schmertmann et al. 1978, Berardi et al. 1991) that base estimates of the settlement of footings in sand on results from in-situ field tests, such as the standard penetration test (SPT) or the cone penetration test (CPT). In Schmertmann's method, the strains are calculated using a strain influence factor and elastic modulus estimated from the CPT cone resistance  $q_c$  for the case of isolated footings. In this paper, following the framework of Schmertmann's method, the interaction effect of neighboring footings on settlement is investigated using the finite element analysis. For this purpose, non-linear finite element analyses are per-

formed for multiple footings separated by different footing distances. Based on results from the finite element analyses, strain influence factors for multiple footings are presented. Design equations of strain influence diagram parameters for multiple footing conditions are presented as well.

## 2 FOOTING SETTLEMENT CALCULATION USING CONE RESISTANCE

Schmertmann's method (Schmertmann 1970, Schmertmann et al. 1978) is essentially an elastic-based approach with modulus values obtained using  $q_c$  and strain influence factor  $I_z$  given in the form of the simplified diagram shown in Figure 1. Other parameters defining the diagram are the value  $I_{z0}$  of the strain influence factor at the footing base, its peak value  $I_{zp}$ , and the depths  $z_{fp}$  to  $I_{zp}$  and  $z_{f0}$  to the bottom of the diagram. The depth  $z_{f0}$  can be referred to as the strain influence depth. As shown in Figure 1, the diagram extends down to  $2B$  and  $4B$ , and the depth  $z_{fp}$  to  $I_{zp}$  is equal to  $0.5B$  and  $B$  for square and strip footings, respectively.

For the implementation of the method, the soil on which the footing rests is divided in several layers based on the  $q_c$  profile, and, with depth and time factors included, the equation for the settlement calculation is given as follows:

$$s = C_1 C_2 (q_b - \sigma'_{v,zf=0}) \sum \left( \frac{I_z \Delta z_i}{E_i} \right) \quad (1)$$

where  $C_1$  and  $C_2$  = depth and time factors;  $\sigma'_{v,zf=0}$  = vertical effective stress at footing base level before the footing was constructed;  $I_{zi}$  = influence factor corresponding to each sublayer;  $\Delta z_i$  = thickness of each sublayer;  $E_i$  = representative elastic modulus of each sublayer. The elastic modulus  $E_i$  of each individual sublayer is obtained from the representative cone resistance  $q_{ci}$  for that sublayer. While  $E/q_c$  is typically taken constant in the conventional Schmertmann method, Lee & Salgado (2002) developed a  $E/q_c$  relationship in terms of the settlement level and the relative density  $D_R$  to account for the non-linearity of the soil stress-strain relationship as follows:

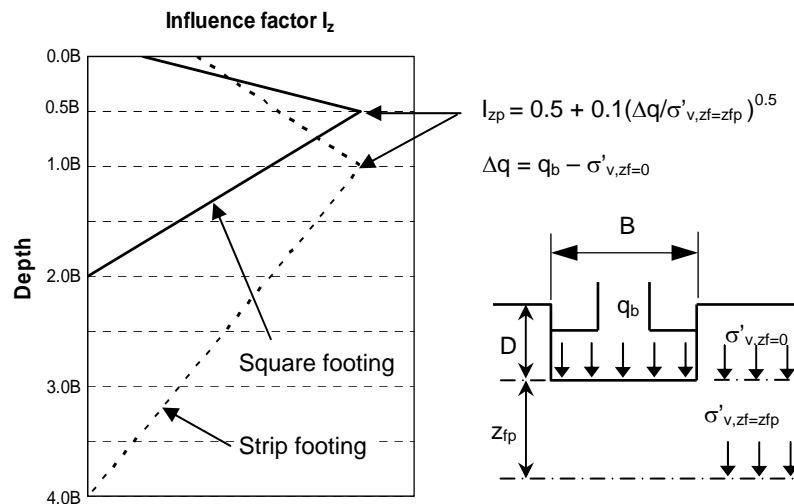


Figure 1. Strain influence diagram for Schmertmann's method.

$$\frac{E}{q_c} = 1.4 \cdot \left( \frac{s}{s_R} \right)^{-0.285} \left( \frac{B}{B_R} \right)^{0.4} \left( \frac{D_R}{100} \right)^{-0.65} \quad (2)$$

where  $s_R$  = reference settlement = 1 cm;  $s$  = settlement in the same unit as  $s_R$ ;  $B_R$  = reference footing width = 1m;  $B$  = footing width in the same unit as the  $B_R$ ; and  $D_R$  = relative density in %.

### 3 FINITE ELEMENT MODELING OF MULTIPLE FOOTINGS

#### 3.1 Soil model

For the finite element analyses of axially loaded multiple footings, the non-linear stress-strain model of Lee & Salgado (1999) was employed. In this model, the elastic modulus is treated as a state-dependent variable and given as follows:

$$\frac{G}{G_o} = [1 - f \left( \frac{\sqrt{J_2} - \sqrt{J_{2o}}}{\sqrt{J_{2\max}} - \sqrt{J_{2o}}} \right)^g] \left( \frac{I_1}{I_{1o}} \right)^{n_g} \quad (3)$$

where  $G$  = secant shear modulus;  $G_o$  = small-strain shear modulus;  $J_2$ ,  $J_{2o}$ , and  $J_{2\max}$  = the current, initial, and maximum second invariants of the deviatoric stress tensor;  $I_1$  and  $I_{1o}$  are the first invariants of the stress tensor at the current and initial states; and  $f$ ,  $g$ , and  $n_g$  = material parameters. Eq. (3) represents the non-linear degradation of the shear modulus from its initial maximum value  $G_o$ .

In order to consider the non-linear characteristics of shear strength for sands, a curved form of the Drucker-Prager failure criterion was adopted employing a state-dependent peak friction angle. For the peak friction angle, the following dilatancy relationship proposed by Bolton (1986) was used:

$$\phi'_p = \phi'_c + AI_R \quad (4)$$

where  $\phi'_p$  = peak friction angle;  $\phi'_c$  = critical-state friction angle;  $A = 5$  and  $3$  for plane-strain and triaxial conditions, respectively. The dilatancy index  $I_R$  is given by:

$$I_R = I_D [10 + \ln\left(\frac{p_A}{100\sigma'_{mp}}\right)] - 1 \quad (5)$$

where  $I_D$  = relative density =  $D_R(\%)/100$ ;  $p_A = 100$  kPa;  $\sigma'_{mp}$  = mean effective stress at peak strength in the same units as  $p_A$ . Eqs. (4) and (5) were used to define the non-linear Drucker-Prager failure surface in the finite element analyses.

#### 3.2 Numerical modeling of multiple footings

Three different cases of multiple-footing configuration were considered in the finite element analysis. These are shown in Figure 2. Cases 1 and 2 correspond to two and three footings in line, respectively, while case 3 corresponds to a five-footing in two perpendicular directions. For each configuration, different footing distances  $L_1$  and  $L_2$  were used in the analyses.

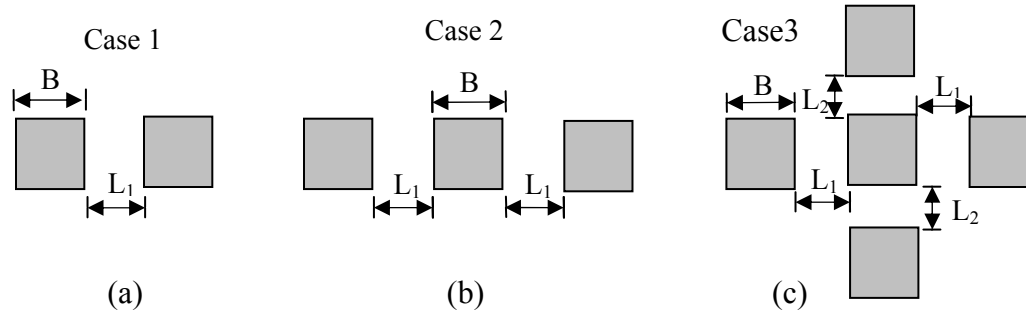


Figure 2. Configuration of multiple footing arrangements in finite element analysis.

The finite element models were constructed using the program ABAQUS with twenty-noded 3D solid elements. The total number of elements for the analysis of a single footing was 12,000. The size of the finite element mesh was 36m (width)  $\times$  42m (length)  $\times$  21m (depth), while the width of footing ( $B$ ) was 1.2m. The size of the mesh represents more than 30 and 17 times the footing width laterally and axially, respectively. Boundary conditions were of the fixed and roller types for the bottom and lateral boundaries, respectively. Loads were applied incrementally to the footings. The soils were assumed in all cases to be dense clean silica sand with  $\gamma = 15.6 \text{ kN/m}^3$  and  $K_0 = 0.5$ . Details on the finite element modeling and soil conditions can also be found in Lee et al. (2008).

## 4 STRAIN INFLUENCE FACTORS FOR MULTIPLE FOOTINGS

### 4.1 Strain influence diagram

Figure 3 shows depth profiles of strain influence factor  $I_z$  for the multiple-footing cases 1, 2, and 3 with different footing distances. In cases 2 and 3, the profiles correspond to those for the center footing. As shown in the figure, the values of  $I_z$  down to the depths at which  $I_z = I_{zp}$  and the value of  $I_{zp}$  itself are nearly constant, irrespective of the distances between the footings and the number of footings considered. The depth to  $I_{zp}$  is also fairly constant, at approximately  $0.5 B$ . Values of  $I_z$  for the part of the influence zone below the peak in the influence diagram increase as the footing distances decrease. For case 1, no significant variation of  $I_z$  values is observed for different footing distance ratios. At a distance ratio  $L_1 = 3.0B$ , the profile is practically indistinguishable from that for a single footing, indicating that there would be no need to account for the interaction between footings for footing distance ratios  $L_1/B$  greater than 3. In the case of the three aligned footings (case 2), it is seen that the  $I_z$  profiles are similar to those of the two side-by-side footings (case 1), but the rate of increase of  $I_z$  with  $L_1/B$  is higher. Similarly to case 1, the effect of footing interaction decreases as the footing distance ratio increases, becoming negligible for distance ratios  $L_1/B$  greater than 3. The lack of dependence of  $I_z$  values on the distance between footings for the zone above the depth to  $I_{zp}$  (observed also in case 1) can be attributed to the fact that load transfer takes place in a direction such that the stress fields caused by each footing separately do not merge for that depth range, even for relatively small spacings.

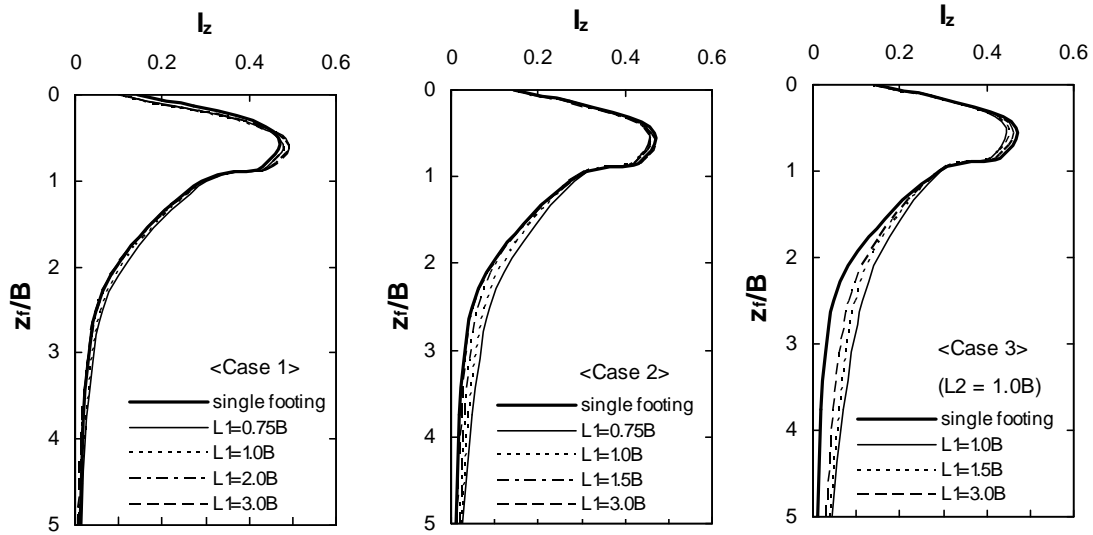


Figure 3. Depth profiles of  $I_z$  for cases 1, 2 and 3.

For case 3 in Figure 3c, compared with results for cases 1 and 2, the increase of  $I_z$  is found to be quite considerable. Since the variation of  $I_z$  values for case 3 results from the combined effects of the two footing distances  $L_1$  and  $L_2$ , the minimum values considered in the analysis for  $L_1/B$  and  $L_2/B$  (both equal to 1) yield the largest increase of  $I_z$  values in Figure 3c.

#### 4.2 Design application

From this study, it was found that the depth of the strain influence zone (i.e.,  $z_{f0}$ ) is the significant component in the strain influence diagram for multiple footings, which varies according to footing distance. Figure 4 shows values of  $z_{f0}/B$  for multiple-footing cases 1, 2 (Fig. 4a) and 3 (Fig. 4b) as a function of the normalized distances  $L_1/B$  and  $L_2/B$ . For cases 1 and 2 with  $L_1/B = 1$ , the strain influence depths were 9 % and 15 % larger than the  $2B$  observed for a single footing, respectively. It is also seen that for  $L_1/B \geq 3$  the influence on the settlement of a given footing on the adjacent footing or footings is negligible.

For case 3, the strain influence depths also vary as a function of the combined effects of the two distances. When both  $L_1/B$  and  $L_2/B$  are larger than 3, there is essentially no interaction between the adjacent footings. For multiple footings with footing distance ratios less than 3, the strain influence diagram developed for a single footing must be modified using Figure 4 for the applicable values of the distance ratios  $L_1/B$  and  $L_2/B$ .

For multiple footings, the key variable that needs to be modified is  $z_{f0}$ . Using the results shown in Figure 4, the equations for  $z_{f0}$  are:

$$\frac{z_{f0}}{B} = 0.22 \cdot \exp \left[ 1.1 \cdot \left( 0.6 - \frac{L_1}{B} \right) \right] + 2 \quad \text{for case 1} \quad (6)$$

$$\frac{z_{f0}}{B} = 0.50 \cdot \exp \left[ 1.2 \cdot \left( 0.6 - \frac{L_1}{B} \right) \right] + 2 \quad \text{for case 2} \quad (7)$$

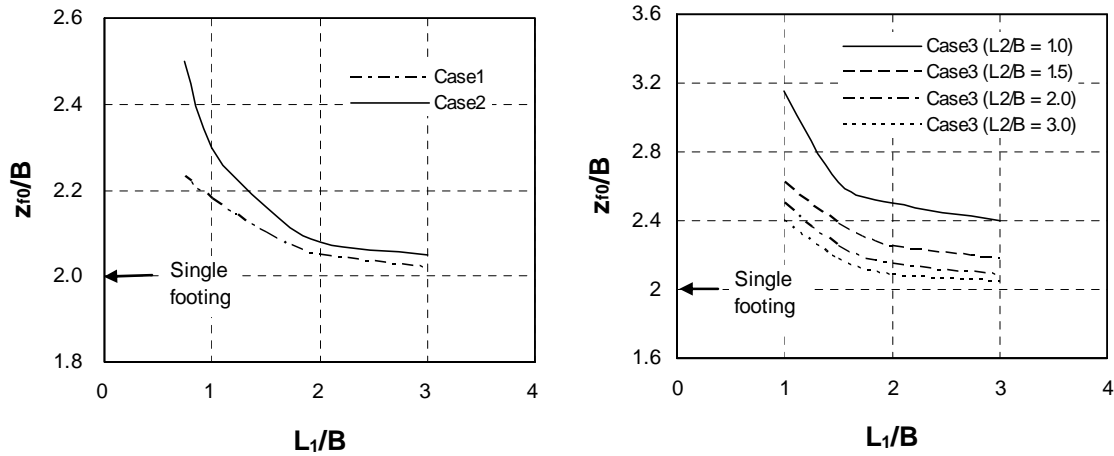


Figure 4. Depth of strain influence zone for cases 1, 2 and 3.

$$\frac{z_{f0}}{B} = 0.83 \cdot \left(\frac{L_2}{B}\right)^{-0.17} \left[ 0.75 \cdot \exp\left[2 \cdot \left(0.75 - \frac{L_1}{B}\right)\right] + 2 \right] \quad \text{for case 3} \quad (8)$$

Once the footing dimensions and configurations are selected, the strain influence diagram shown in Figure 1 can be reconstructed using  $z_{f0}$  calculated from Eqs. (6) to (8).

## 5 SUMMARY AND CONCLUSIONS

Shallow foundations typically consist of multiple footings. Most conventional methods used for the estimation of footing settlement have been developed for an isolated footing, and do not provide a way to account for interaction between adjacent footings. In this paper, a method of settlement estimation that takes account of the proximity of neighboring footing was presented based on Schmertmann's framework. Three-dimensional nonlinear finite element analyses were performed to obtain the load-settlement responses and strain distributions in the foundation soils under multiple footing conditions. Three different arrangements of square footings at different distances were considered in the finite element analyses. The finite element analyses produced values of  $I_z$  for two, three and five footings arranged in various ways.

The results of the analyses show that the depth of the strain influence zone in the strain influence diagram needs to be modified to account for the interaction between footings. New strain influence diagrams for multiple footing conditions were presented. These were mainly based on the diagram of Schmertmann's method proposed for a single footing, with corrected depth of the strain influence zone as a function of  $L_1/B$  and  $L_2/B$  for various multiple footing configurations. Design equations for the influence depths associated with the modified strain influence diagrams obtained from the finite element analyses were presented as well.

## 6 REFERENCES

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